COLLEGE OF ENGINEERING



PROJECT SPONSOR OSU SEED LAB

- Official Seed Lab of Oregon State University and is a part of AOSA AND ISTA. The lab offers a wide range of testing that includes purity, germination, moisture content and many others.
- Seed lab processes over 12,000 samples of seed yearly.
- Current process is labor intensive and takes technicians 10-15min/sample





FIGURE 1: GAMET SEED DIVIDER



AUTOMATED SEED GAMET

Project Objective: Create a automated device capable of obtaining homogenized 5g and 45g samples that will be used for seed analysis

WHAT IS A SEED GAMET DIVER?

- Seed Gamet Dividers (GSD, Figure 1) are used to divide seed samples in two. Every time a sample is poured into the system yield is halved.
- The system is used not only for homogenization but also the division process

HOW IT WORKS

- System uses 4 linear actuators to bring the seed from the disposal shoots back up to the top hopper.
- The arm assembly then pours the seeds back into the hopper and the cycle continues until final samples are achieved.
- The system is controlled using Arduino logic that is driven by the weight being output by the loadcells.



SAMPLING PROCESS

- Cycle is broken into two steps 1) Homogenization 2) Seed Division.
- During homogenization seeds are cycled through the Gamet three times to ensure [an even distribution of all materials in the sample] all dirt and debris are mixed through the entire sample.
- During division, the sample is divided down in order to obtain a 5g and 45g sample.
- Each time seed in poured into the machine, it is halved and exits out the side spouts.









AUTOMATED SEED GAMET 2021 - 2022



ARM ASSEMBLY

- Load cell (measure cup contents)
- Shaft Mounting Tube (custom prt)
- Motor shaft (custom prt)
- Mounting plate (custom part)
- Servo motor (pour out cup contents)



/ put your setup code here, to run once

put your main code here, to run repeatedl

CONTROLS

- Arduino MEGA
- Stepper Drivers
- 24V power supply
- Bread Board
- LCD Screen/ Button Panel

SOFTWARE

• C++ 700 plus lines of code • 20+ code iterations • Stepper control Servo Control Load Cell control

THE TEAM

- Adam Bischoff ME & MFGE
- Andrew Kuenzi ME
- Brayden Reiland ME & MFGE
- Marcus Rosette ME & MFGE